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ABSTRACT OF THE DISCLOSURE

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In one embodiment of the invention, a captive propelled model is provided comprising a balancing member having a pivoting pin disposed between two ends of the balancing member. A figurine having an actuator and at least one actuable member is disposed near one end of the balancing member, and a counterweight is disposed near the opposite end. A platform for the device includes wiring for connecting a power supply to the actuator. In a further embodiment of the invention, a conductive member is disposed so as to receive the pivoting pin and thereby establish an axis of rotation about which the balancing member rotates when propelled by the actuable member. The conductive surface is also in contact with a drag-line or the like that is suspended from the balancing member to establish an electrical ground for the power supply circuit. In a further embodiment of the invention, a captive propelled model further comprises a remote controller, a switch having a receiver to receive a control signal from the remote controller, and associated wiring and connections so that an operator can control the device remotely.